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DATE: Monday, March 28, 2005

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<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>			
<input type="checkbox"/>	L7	L4 and position error	4
<input type="checkbox"/>	L6	L3 and l4	4
<input type="checkbox"/>	L5	(l3 or L4) and position error	11136
		(5944475 6213853 6213853 6227946 6242879 5833426 6024107 6073828 4854623 4897015 5007784 5429251 5452521 5607276 5613821 5651823 5664925 5746460 5778554 5783834 5789890 5795355 5803979 5810549 5870488 5905850 5954840 5967578 5993142 5993141 6012470 6037733 6059516 6059516 6085670 6121743 6164894 6202482 6205852 6213136 6213136 6256555 6267423 6275748 6283355 6293749 6298280 6326755 6350177 6360144).pn.	82
<input type="checkbox"/>	L3	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and position error	11136
<input type="checkbox"/>	L2	bacchi.in. and position error	5
<input type="checkbox"/>	L1	robot and specimen and position error	15

END OF SEARCH HISTORY

The search results page from Google. At the top, there's a navigation bar with links for Web, Images, Groups, News, Froogle, Local^{New!}, more », Advanced Search, and Preferences. Below the navigation bar is a search bar containing the query "robot arm" and "position error". To the right of the search bar are two buttons: "Search" and "Advanced Search". Below the search bar, a message states: "The 'AND' operator is unnecessary -- we include all search terms by default. [details]".

WebResults 1 - 10 of about 614 for "robot arm" and "position error". (0.42 seconds)

Tip: Save time by hitting the return key instead of clicking on "search"

[PDF] Distributed Digital Control of a Robot ArmFile Format: PDF/Adobe Acrobat - [View as HTML](#)... outline a system developed for control of a PUMA 560 **robot arm** that uses a ... While operating with a PD control loop, the maximum **position error** (while tracking ...www.itee.uq.edu.au/~wyeth/Publications/puma.PDF - [Similar pages](#)**[PDF] Positioning a Robot Arm: an Adaptive Neural Approach Introduction**

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[PDF] **PARAMETER IDENTIFICATION OF A ROBOT ARM USING GENETIC ALGORITHMS**

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